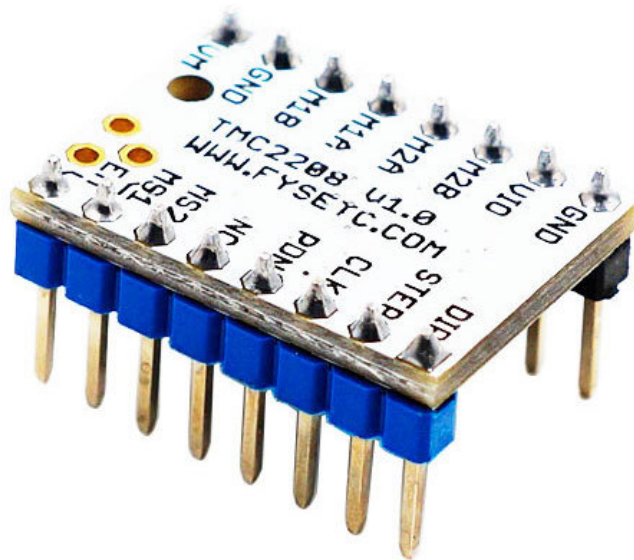


TMC2208

Product Introduction



TMC2208 is an ultra-quiet two-phase stepper motor drive chip, continuous drive current 1.4A, peak current 2A, voltage range 4.75V-36V, 256 subdivision. The flexible microPlyer interpolation unit provides up to 256 subdivisions, allowing perfect sinusoidal control even in systems with limited pulse frequencies; these are also designed because stealthChop2 ultra-quiet technology is widely used in 3D printing. Compatible with existing 3D printer electronics, eliminating the expensive costs of redesign. With a standard step/dir interface, it is easy to use. It can replace the original TMC2100, lower heat, especially for 3D printing market.

Features

- UART configuration interface (9600-500k Baud)
- Power tube built-in drive current 1.4A ,peak current 2A, voltage range 4.75V-36V
- Up to 256 native microsteps (without interpolation)
- CoolStep™ current dynamic adjustment technology, can save 70% of the energy
- stealthChop2 - faster motor acceleration/deceleration than stealthChop
- dcStep™, stallGuard2™ stall detection technology
- Automatic stealthChop and spreadCycle switchover depending on velocity
- Hardware compatible with StepStick and Pololu A4988 Stepper Driver
- Components on bottom PCB side for better heat emission
- Automatic standby current reduction
- SteaClthhop mute technology
- spreadCycle - highly dynamic motor control chopper

Technical Specifications

Model	TMC2208
Interface	Step/Dir
Configuration	CFG Pins or UART
Native Microsteps	up to 1/256
microPlyer Microsteps	1/256
Logic Voltage (VIO)	3-5V
Motor Voltage (VM)	5.5-36V
Motor Phase Current max	1.2A RMS, 2.0A Peak
Internal V- Regulator	enabled
RDSon	<=0.3 Ohm
stealthChop (quiet)	yes
spreadCycle	yes
coolStep	no
stallGuard	no
dcStep	no

Pin Functions

TMC2208

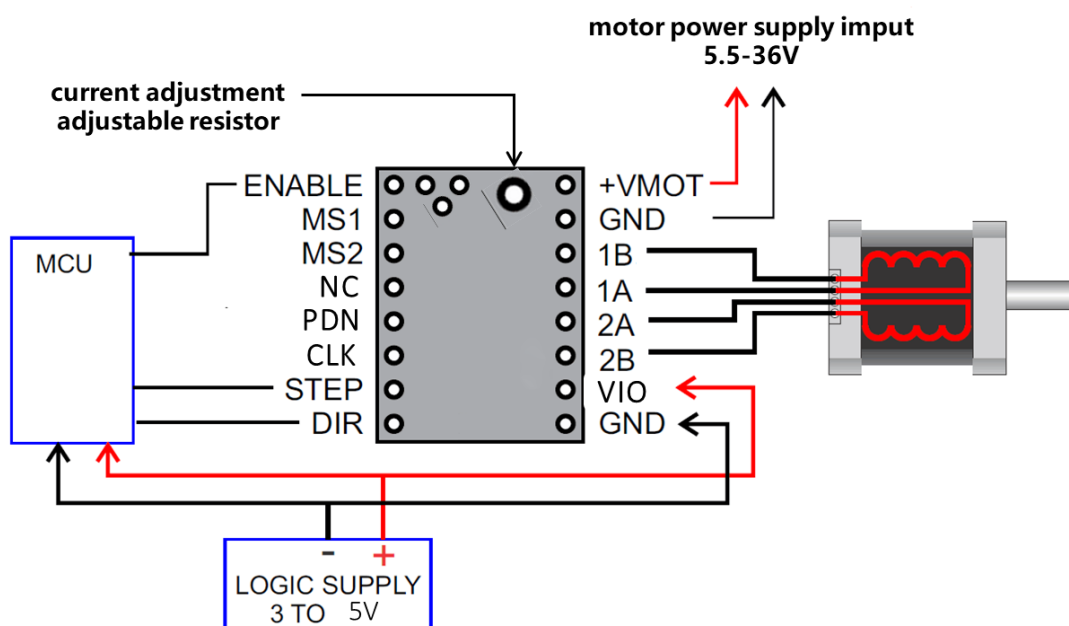
Motor Drive Pin Descriptions

GND	GND	DIR	DIR
VIO	VIO	STEP	STEP
M2B	M2B	CLK	CLK
M2A	M2A	PDN	PDN
M1A	M1A	NC	NC
M1B	M1B	MS2	MS2
GND	GND	MS1	MS1
VM	VM	EN	EN

Pin	Function
Power Supply	
GND	Ground
VM	Motor Supply Voltage
VIO	Logic Supply Voltage
Motor Outputs	
M1A	Motor Coil 1
M1B	Motor Coil 1
M2A	Motor Coil 2
M2B	Motor Coil 2
Control Inputs	
STEP	Step-Signal Input
DIR	Direction-Signal Input
TMC2208	
EN	Enable Motor Outputs: GND=on, VIO=off
MS1	Step-Configuration
MS2	Step-Configuration
PDN	UART and Auto Power Down Control: GND=on, VIO=off
CLK	Clock Input
DIAG	Diagnostics Output
INDEX	Index Output

Interface Resources

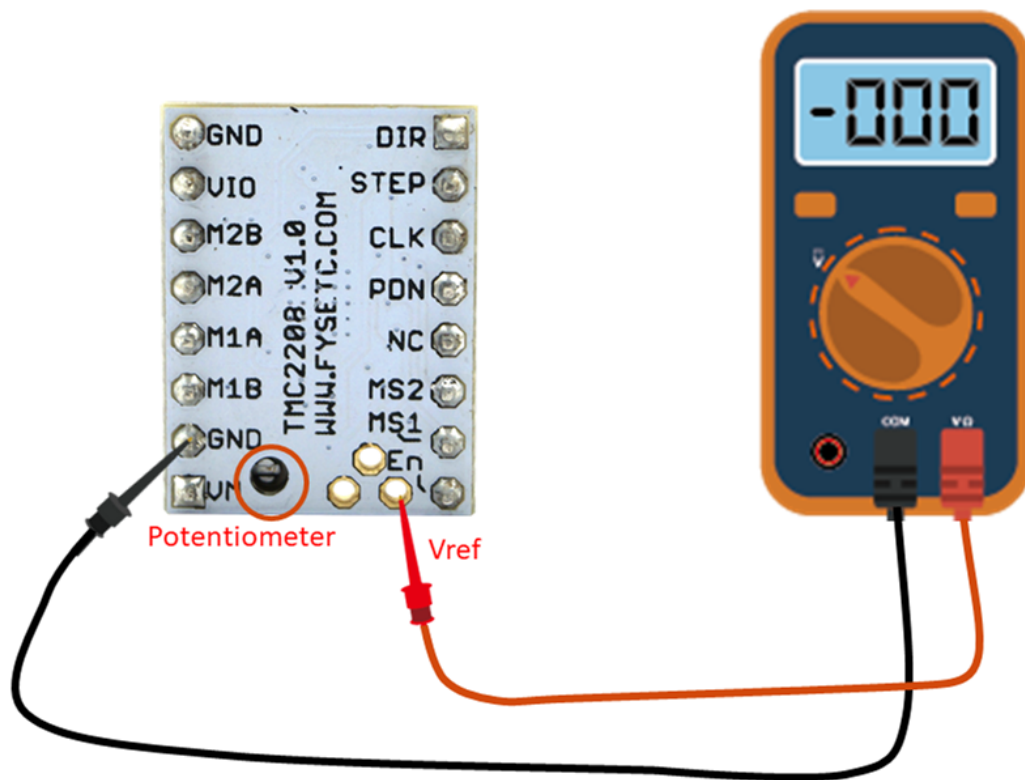
Wiring Diagram



Tip

The TMC2208 outputs continuous motor current up to 1.4A and peak current up to 2A. Therefore, the reference voltage of the driver module should not exceed 1V. At the same time, the driver module must be dissipated, otherwise it will affect the life of the driver module.

Motor Current Setting



The best way to set the motor current is by measuring the voltage on the Vref pin (0...2.5V) and adjusting the voltage with the potentiometer. The maximum settable motor current is 1.77A RMS (0.110hm sense resistors), but the SilentStepSticks can only be used up to 1.2A RMS.

$$I_{rms} = (V_{ref} * 1.77A) / 2.5V = V_{ref} * 0.71$$

$$V_{ref} = (I_{rms} * 2.5V) / 1.77A = I_{rms} * 1.41 = I_{max}$$

Vref -> Voltage on Vref pin

I_{rms} -> RMS (Root Mean Square) current per phase ($I_{rms} = I_{max} / 1.41$)

I_{max} -> Maximum current per phase ($I_{max} = I_{rms} * 1.41$)

Note

1. Vref measures Gnd and the voltage at the middle of the potentiometer.
2. Do not connect the motor when measuring the voltage, otherwise it is easy to burn the driver.
3. Power should be connected when measuring voltage, do not just connect USB power supply.
4. **Please pay special attention to directions!**

Calculator

RMS Current (A): 0.6

Reference Voltage (V):

Micro-stepping

MS2(-)	MS1(-)	Steps(-)	Interpolation(-)	Mode(-)
GND	VIO	$1/2$	$1/256$	stealthChop2
VIO	GND	$1/4$	$1/256$	stealthChop2
GND	GND	$1/8$	$1/256$	stealthChop2
VIO	VIO	$1/16$	$1/256$	stealthChop2

Setting Method

With the TMC2208 Configurator you can change the settings and program the OTP (One-Time-Programmable) memory of a Trinamic TMC2208 via the UART interface.

To run the program:

1. Install ScriptCommunicator
2. Download TMC2208.sceZ
3. Start the TMC2208.sceZ file with the ScriptCommunicator:
ScriptCommunicator TMC2208.sceZ
4. Choose the right serial port and click Connect
5. Modifications in the Configurator are directly transmitted



The
OTP
bits
can
be
programmed
only
one
time.
If
you
enable
spreadCycle
then
TOFF
cannot
be
0
(null).

Hardware Connection

You
can
use
every
RS232
serial
adapter
with
0-5V
logic

levels
(e.g.
FTDI-
Breakout)
and
the
SilentStepStick
Tester/Programmer
can
be
used
as
connection
adapter.



The
jumper
next
to
the
PDN_UART
pin
has
to
be
closed
on
the
TMC2208
SilentStepStick
to
enable
the

pin
access
via
the
pin
header.

Versions
Difference

